STUDY MODULE DESCRIPTION FORM								
Name of the module/subject Automatics and Robotics					Coo 101	^{de} 10601131010622491		
Field of study						Year /Semester		
Aerospace Engineering				(general academic, practical) (brak))	2/3		
Elective path/specialty				Subject offered in:		Course (compulsory, elective)		
Safety and Management of Aviation			_	Polish		obligatory		
Cycle of study: Form of study (full-time,part-time)								
First-cycle studies				full-time				
No. of hours						No. of credits		
Lecture: 1 Classes: - Laboratory: -				Project/seminars: - 1				
Status o	-	program (Basic, major, other) (brak)	((university-wide, from another field) (brak)				
Educatio	on areas and fields of scie	. ,		ECTS distribution (number				
						and %)		
Resp	onsible for subje	ect / lecturer:	Re	sponsible for subje	ct /	lecturer:		
-	D Wojciech Sawczuk			M.Eng Julian Kominowski				
ema	il: wojciech.sawczuk@	put.poznan.pl		email: julian.kominowski@	put.p	poznan.pl		
	61 224 4510 ulty of Transport Engir	neering		tel. 61 665 2841 Faculty of Transport Engineering				
	rowo 3 Street, 60-965	0		Piotrowo 3 Street, 60-965 Poznan				
Prere	quisites in term	s of knowledge, skills an	d se	ocial competencies:				
	Knowledge	The student has a basic knowled						
1	Knowledge	owledge telecommunications, knows the basics of the theory of probabilistic processes, harmonic signals and graph theory.						
2	Skills	Student is able to apply his know	wledge in learning about and solving automation problems.					
3	Social	The student is able to determine the priorities important in solving the tasks posed before him, he can effectively collaborate in the group taking on different roles.						
A.c.c.u	competencies	-	uie (group taking on unerent to	163.			
Assumptions and objectives of the course: Understanding the role of automation in transport and mechanics as well as improving efficiency and effectiveness in traffic management and vehicle monitoring.								
manag		mes and reference to the	ed	ucational results for	a f	ield of study		
Know	/ledge:		cu		uı			
 has knowledge in the field of mathematics, including algebra, analysis, theory of differential equations, probabilistic, analytical geometry necessary for: description of the operation of discrete mechanical systems, understanding of computer graphics methods, description of the operation of electrical and mechatronic systems - [K1A_W01] 								
2. has a structured, theoretically founded general knowledge covering key issues in the field of on-board equipment, as well as on-board and ground-based electronic communication systems - [K1A_W09]								
	a structured, theoretic ment - [K1A_W12]	ally founded general knowledge c	over	ing key issues in the field o	of flig	ght safety and hazard risk		
Skills								
 knows how to use native and international languages to the extent that it allows to understand technical texts and write technical descriptions of machines in the field of aviation and astronautics (technical terminology) - [K1A_U01] 								
2. is able to communicate using various techniques in a professional environment and other environments using a formal								
record of construction, technical drawing, concepts and definition of the scope of the studied field of study - [K1A_U02] 3. can obtain information from literature, the Internet, databases and other sources. Can integrate the information obtained and interpret conclusions and create and justify opinions - [K1A_U04]								
Social competencies:								
1. understands the need to learn throughout life; can inspire and organize the learning process of other people - [K1A_K01]								
2. is aware of the importance and understands the non-technical aspects and effects of engineering activities, including its impact on the environment, and the related responsibility for decisions - [K1A_K02]								

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Assessment methods of study outcomes				
Final test				
Course description				
1. Definition of control, control device and automatic control,				
2. Definition of the set point, current value and control force,				
3. Definition of the controller, setting variable and control variable,				
4. Diagram and description of the open and closed control system,				
5. The system of regulation in a steady state and undetermined state and what conclusions result	from it,			
6. Types, characteristics of input signals and their equations,				
7. Transmission and spectral transmittance, formulas and example,				
8. The essence of Laplace's transformation, an example of any two transformations,				
9. Kinds of elements appearing in the automatic control system with the diagram,				
10. Connecting elements (serial, parallel, with feedback) patterns and examples,				
11. Types of linear elements, functions f (t), transmittances, characteristics, and examples,				
12. Frequency characteristics of Nyquist and Bego, examples on any elements,				
13. Study of static and dynamic properties (static and dynamic characteristics),				
14. Time constant and period, methods of determination on the example of any member,				
15. Tasks of regulators in the automatic control system,				
16. Distribution of regulators with description and examples,				
17. Characteristics of P, I, PI, PD and PID regulators,				
18. Error and dead zone of selected regulators,				
19. Time of integration and differentiation time on the example of selected regulators,				
20. Time courses on the output for ideal and real controllers.				
Basic bibliography:				
1. Żelazny M., Podstawy automatyki, Materiały pomocnicze do wykładu				
2. Rumatowski K., Podstawy automatyki cz.1, Wydawnictwo Politechniki Poznańskiej 2004				
3. Rumatowski K., Podstawy automatyki cz.2, Wydawnictwo Politechniki Poznańskiej 2004				
4. Urbaniak A., Podstawy automatyki, Wydawnictwo Politechniki Poznańskiej 2001				
Additional bibliography:				
1. Horla D., Podstawy automatyki, Wydawnictwo Politechniki Poznańskiej 2003				
2. Wiak S., Mechatronika cz.2, Wydawnictwo Politechniki Łódzkiej 2010				
Result of average student's workload				
Activity	Time (working hours)			
1. Preparation for the lecture	1			
2. Participation in the lecture	15			
3. Strengthening the content of the lecture	1			
4. Consultations for the lecture	1			
5. Preparation for the exam	1			

6. Participation in the exam

Student's workload

Source of workload	hours	ECTS
Total workload	21	1
Contact hours	16	1
Practical activities	0	0